

Predicate-Based Model Checking

Dirk Beyer

LMU Munich, Germany



Based on:

Dirk Beyer, Matthias Dangl, Philipp Wendler:

A Unifying View on SMT-Based Software Verification

Journal of Automated Reasoning, Volume 60, Issue 3, 2018.

<https://doi.org/10.1007/s10817-017-9432-6>

preprint: [online on CPACHECKER website](#) under
“Documentation”

SMT-based Software Model Checking

- ▶ **Predicate Abstraction**
(BLAST, CPACHECKER, SLAM, ...)
- ▶ **IMPACT**
(CPACHECKER, IMPACT, WOLVERINE, ...)
- ▶ **Bounded Model Checking**
(CBMC, CPACHECKER, ESBMC, ...)
- ▶ **k -Induction**
(CPACHECKER, ESBMC, 2LS, ...)

Base: Adjustable-Block Encoding

Originally for predicate abstraction:

- ▶ Abstraction computation is expensive
- ▶ Abstraction is not necessary after every transition
- ▶ Track precise path formula between abstraction states
- ▶ Reset path formula and compute abstraction formula at abstraction states
- ▶ Large-Block Encoding:
abstraction only at loop heads (hard-coded)
- ▶ Adjustable-Block Encoding:
introduce block operator "blk" to make it configurable

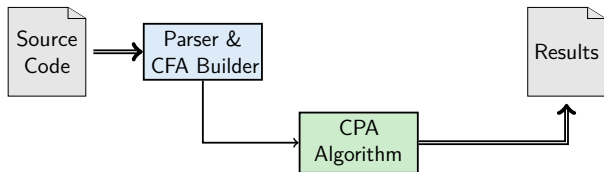
Base: Configurable Program Analysis

Configurable Program Analysis (CPA):

- ▶ Beyer, Henzinger, Théoduloz: [CAV'07]
- ▶ One single unifying algorithm for all algorithms based on state-space exploration
- ▶ **Configurable** components: abstract domain, abstract-successor computation, path sensitivity, ...

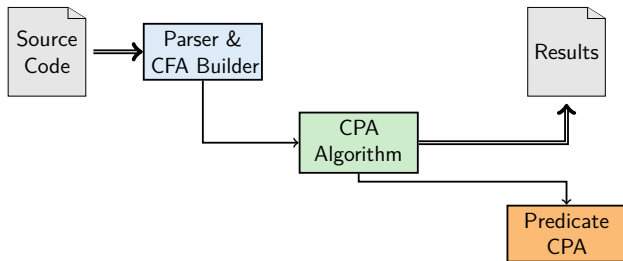
Using the CPA Framework

- ▶ CPA Algorithm is a configurable reachability analysis for arbitrary abstract domains



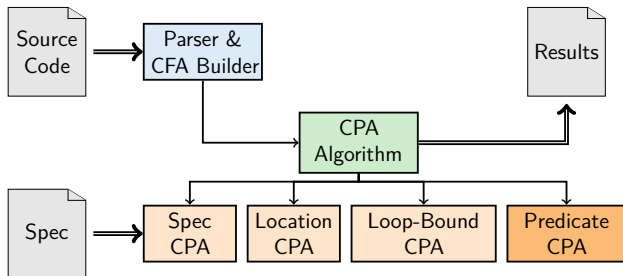
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- ▶ Provide Predicate CPA for our predicate-based abstract domain



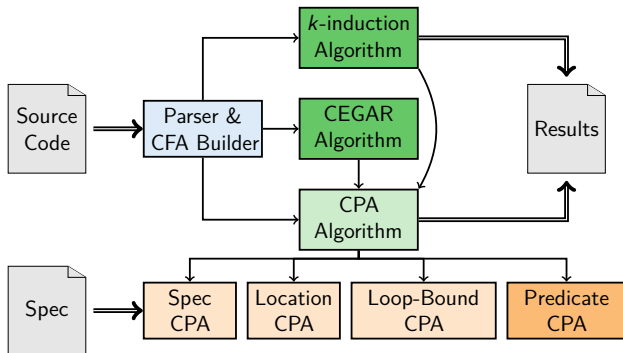
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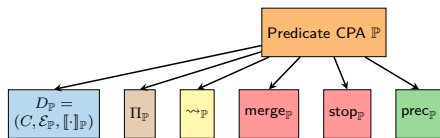


Using the CPA Framework

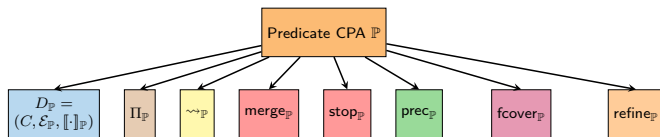
- ▶ CPA Algorithm is a configurable reachability analysis for arbitrary abstract domains
- ▶ Provide Predicate CPA for our predicate-based abstract domain
- ▶ Reuse other CPAs
- ▶ Built further algorithms on top that make use of reachability analysis



Predicate CPA



Predicate CPA



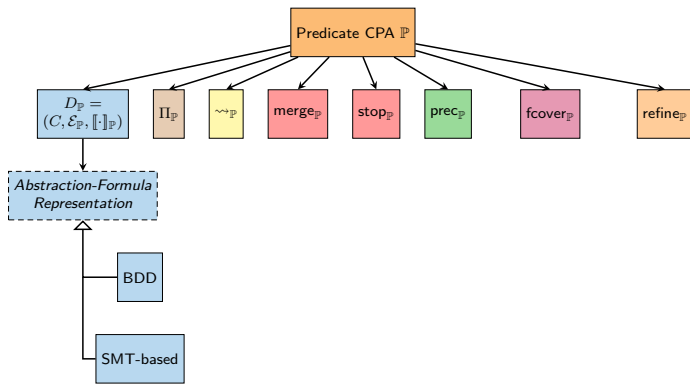
Predicate CPA: Abstract Domain

- ▶ Abstract state: (ψ, φ)
 - ▶ tuple of abstraction formula ψ and path formula φ (for ABE)
 - ▶ conjunctions represents state space
 - ▶ abstraction formula can be a BDD or an SMT formula
 - ▶ path formula is always SMT formula and concrete

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 - ▶ path formula is always SMT formula and concrete
- ▶ Precision: set of predicates (per program location)

Predicate CPA



Predicate CPA: CPA Operators

- ▶ Transfer relation:
 - ▶ computes strongest post
 - ▶ changes only path formula, new abstract state is (ψ, φ')
 - ▶ purely syntactic, cheap
 - ▶ variety of encodings using different SMT theories possible (different approximations for arithmetic and heap operations)

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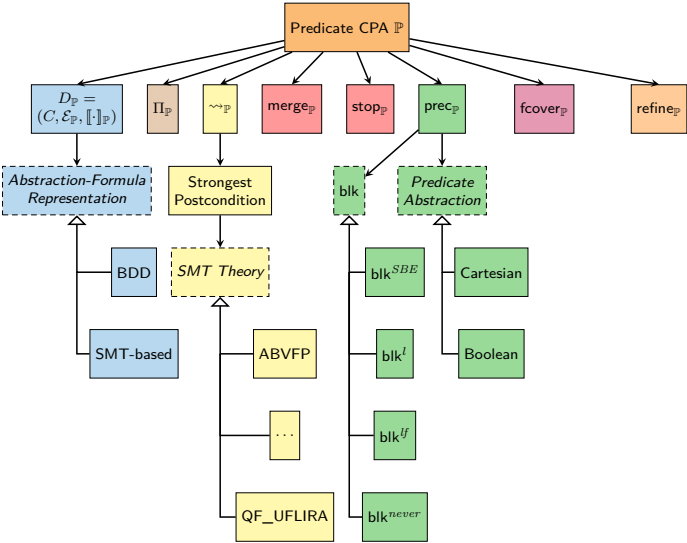
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- ▶ Precision-adjustment operator:
 - ▶ only active at block ends (as determined by blk)
 - ▶ computes abstraction of current abstract state
 - ▶ new abstract state is $(\psi', true)$

Predicate CPA

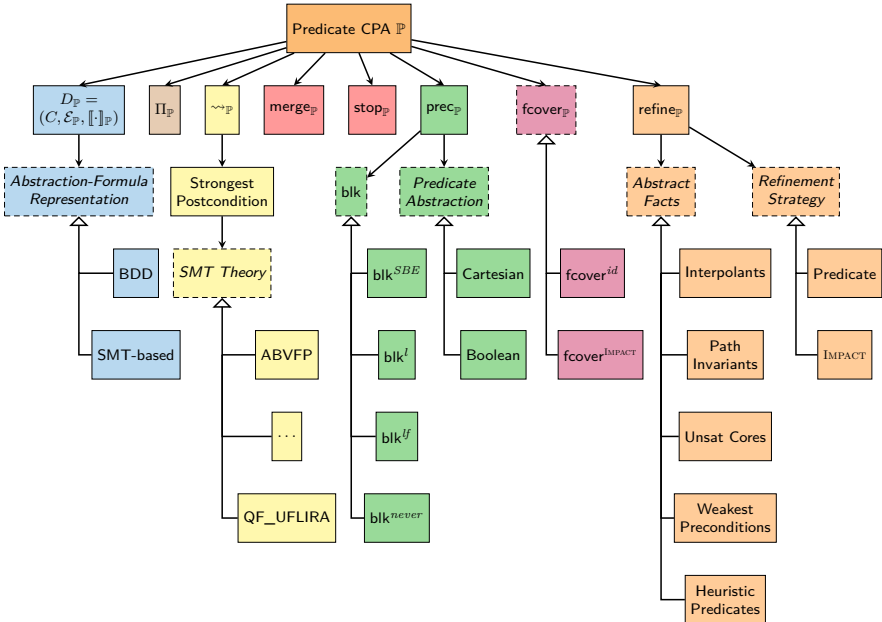


Predicate CPA: Refinement

Four steps:

1. Reconstruct ARG path to abstract error state
2. Check feasibility of path
3. Discover abstract facts, e.g.,
 - ▶ interpolants
 - ▶ weakest precondition
 - ▶ heuristics
4. Refine abstract model
 - ▶ add predicates to precision, cut ARGor
 - ▶ conjoin interpolants to abstract states, recheck coverage relation

Predicate CPA



Predicate Abstraction

- ▶ Predicate Abstraction
 - ▶ [CAV'97, POPL'02, J. ACM'03, POPL'04]
 - ▶ Abstract-interpretation technique
 - ▶ Abstract domain constructed from a set of predicates π
 - ▶ Use CEGAR to add predicates to π (refinement)
 - ▶ Derive new predicates using Craig interpolation
 - ▶ Abstraction formula as BDD

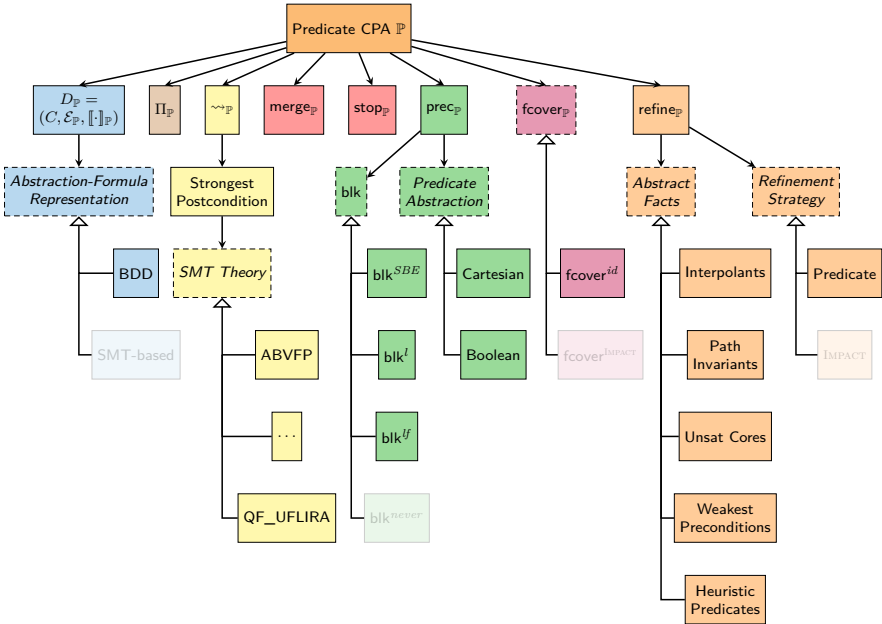
Expressing Predicate Abstraction

- ▶ Abstraction Formulas: BDDs
- ▶ Block Size (blk): e.g. blk^{SBE} or blk^l or blk^{lf}
- ▶ Refinement Strategy: add predicates to precision, cut ARG

Use CEGAR Algorithm:

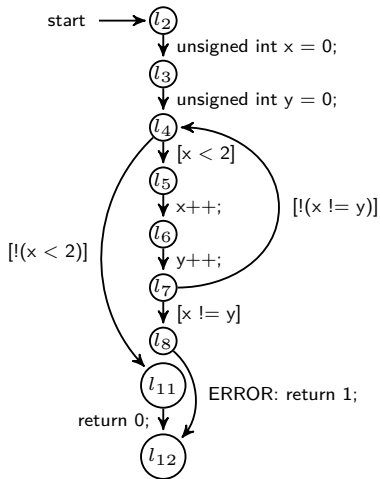
- 1: **while** *true* **do**
- 2: run CPA Algorithm
- 3: **if** target state found **then**
- 4: call refine
- 5: **if** target state reachable **then**
- 6: **return** *false*
- 7: **else**
- 8: **return** *true*

Predicate CPA

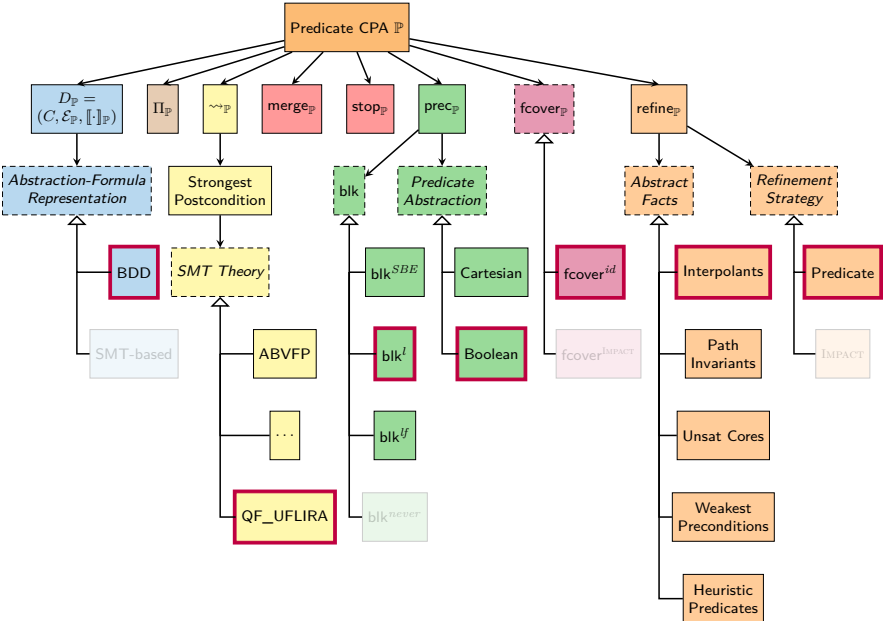


Example Program

```
1  int main() {  
2      unsigned int x = 0;  
3      unsigned int y = 0;  
4      while (x < 2) {  
5          x++;  
6          y++;  
7          if (x != y) {  
8              ERROR: return 1;  
9          }  
10     }  
11     return 0;  
12 }
```

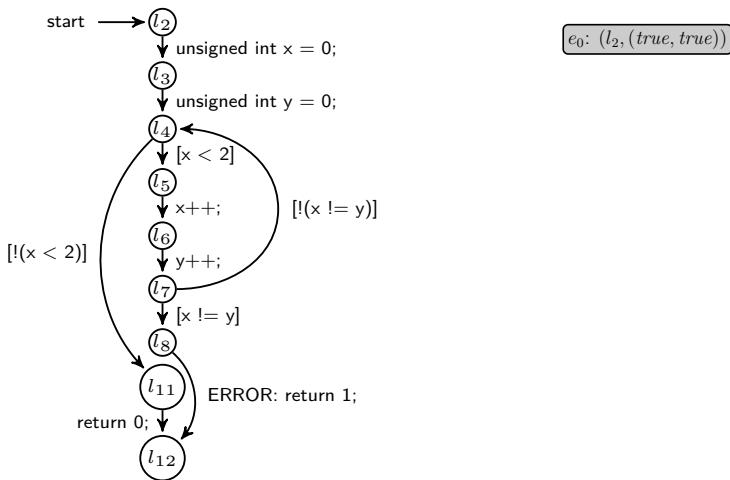


Predicate CPA



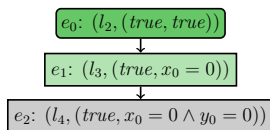
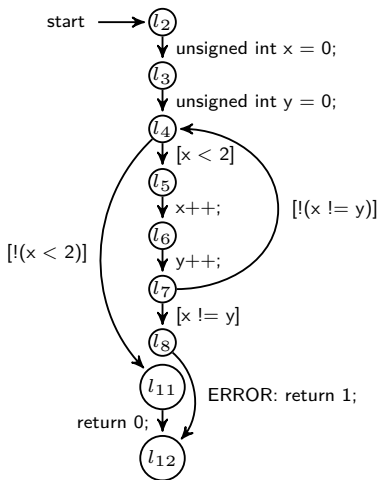
Predicate Abstraction: Example

with blk^l , $\pi(l_4) = \{x = y\}$ and $\pi(l_8) = \{\text{false}\}$



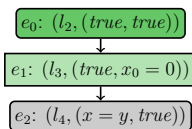
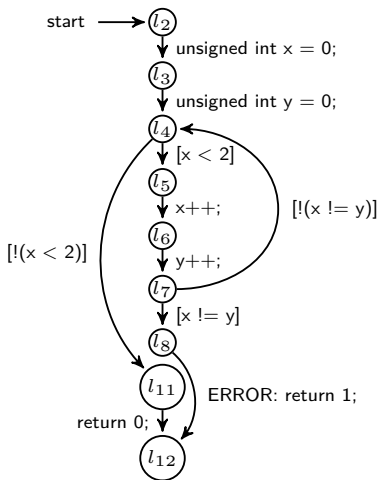
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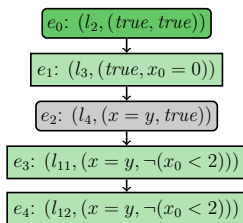
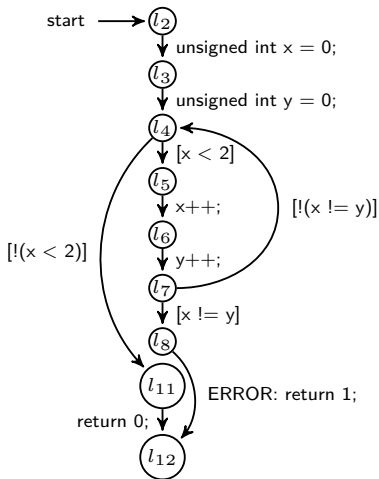
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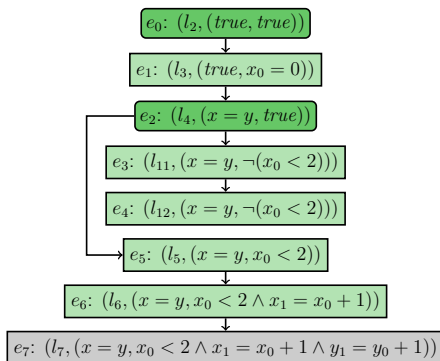
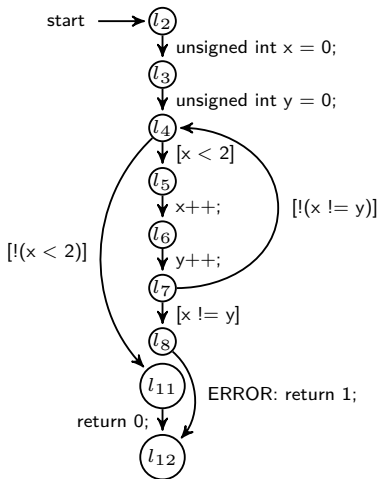
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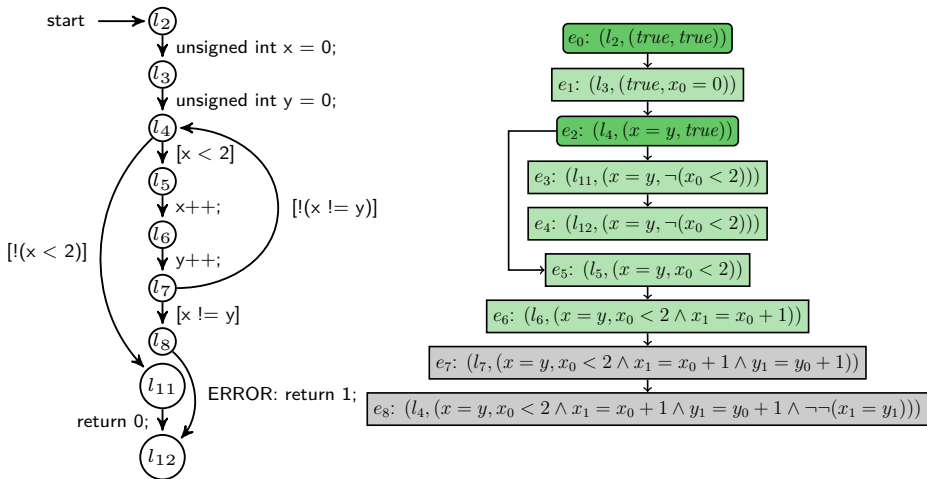
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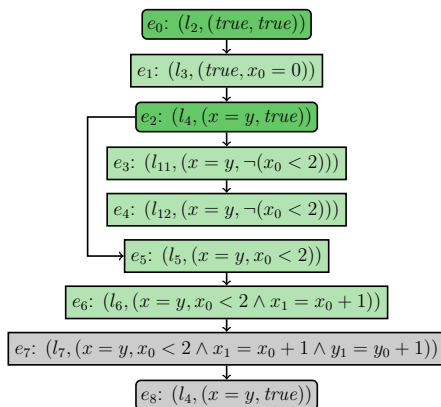
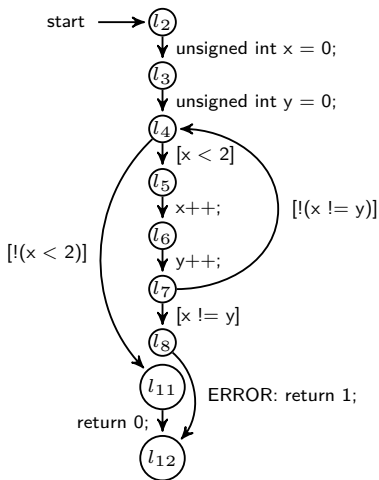
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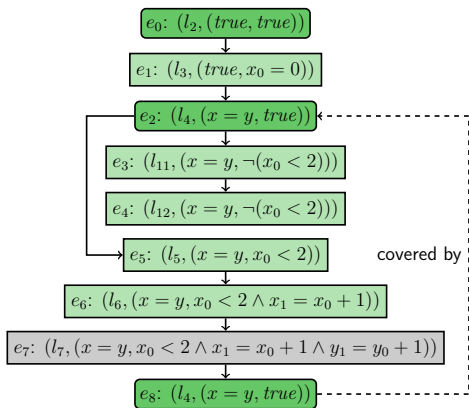
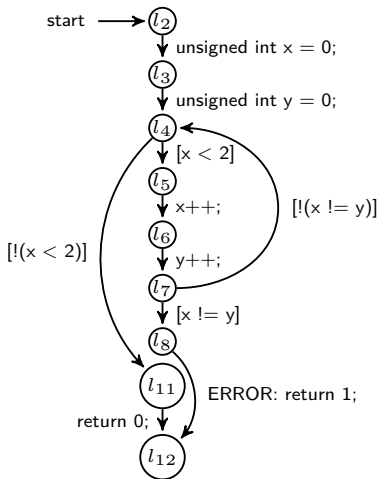
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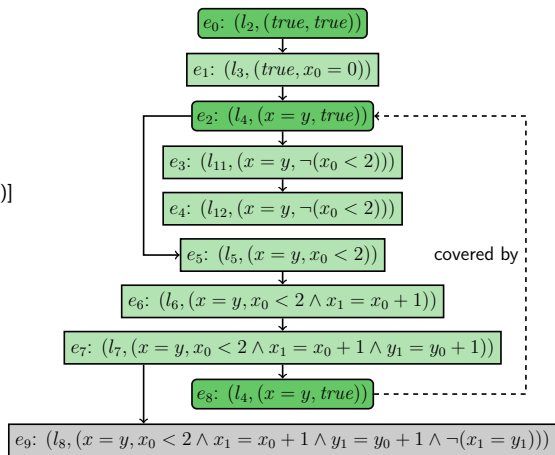
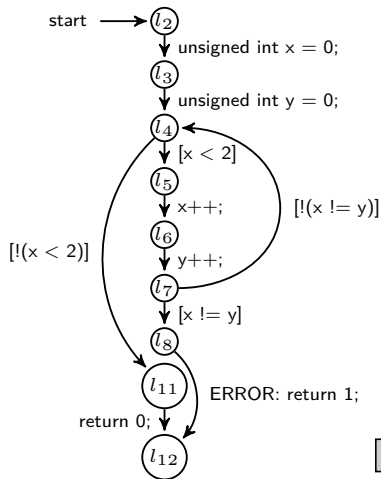
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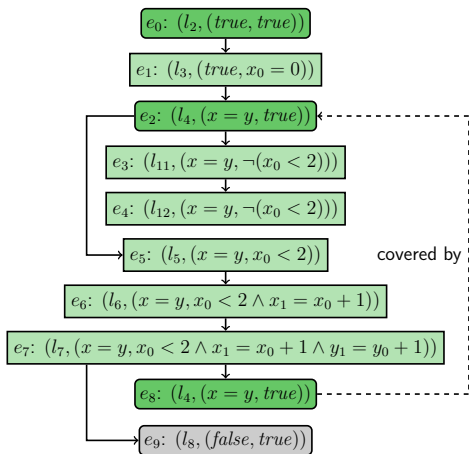
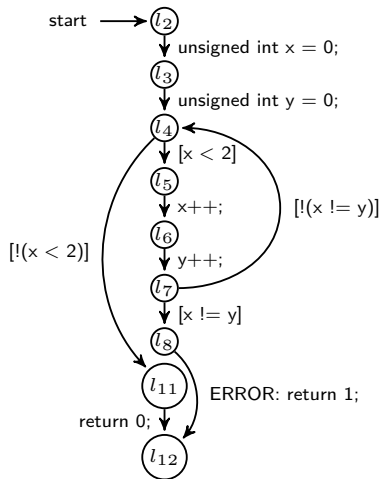
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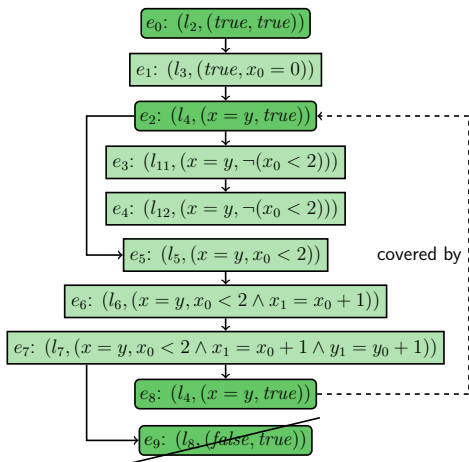
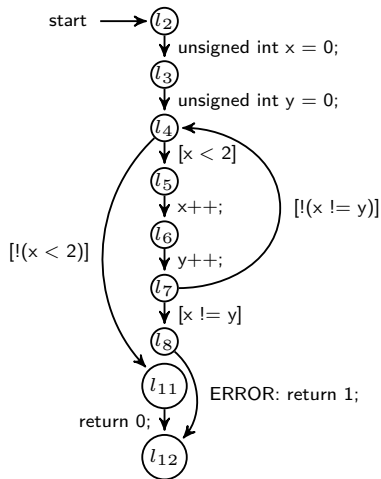
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- ▶ IMPACT
 - ▶ "Lazy Abstraction with Interpolants" [CAV'06]
 - ▶ Abstraction is derived dynamically/lazily
 - ▶ Solution to avoiding expensive abstraction computations
 - ▶ Compute fixed point over three operations
 - ▶ Expand
 - ▶ Refine
 - ▶ Cover
 - ▶ Abstraction formula as SMT formula
 - ▶ Optimization: forced covering

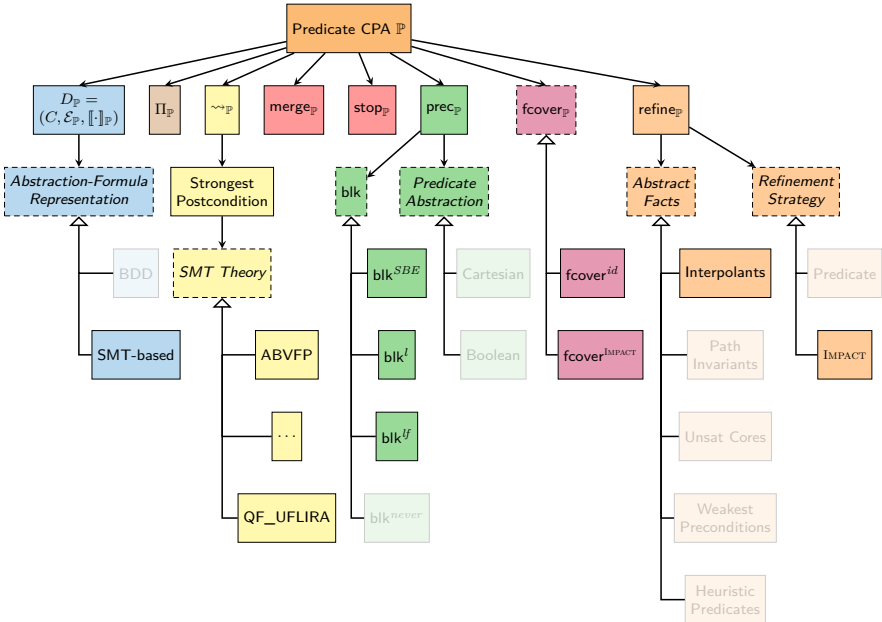
Expressing IMPACT

- ▶ Abstraction Formulas: SMT-based
- ▶ Block Size (blk): blk^{SBE} or other (new!)
- ▶ Refinement Strategy:
conjoin interpolants to abstract states,
recheck coverage relation

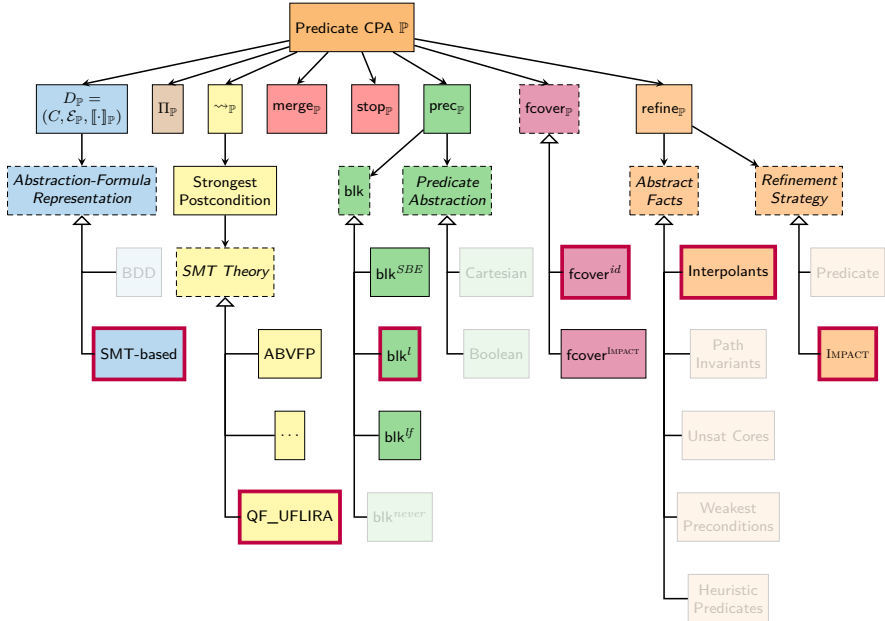
Furthermore:

- ▶ Use CEGAR Algorithm
- ▶ Precision stays empty
→ predicate abstraction never computed

Predicate CPA

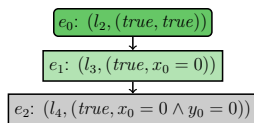
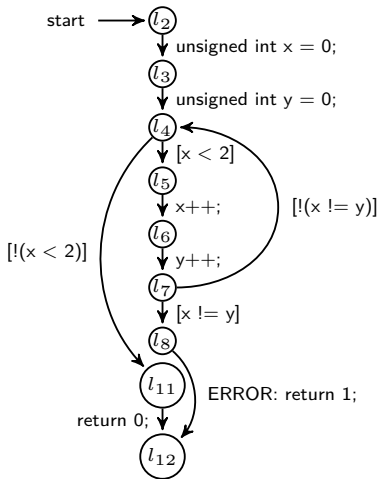


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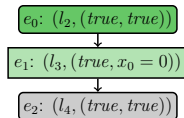
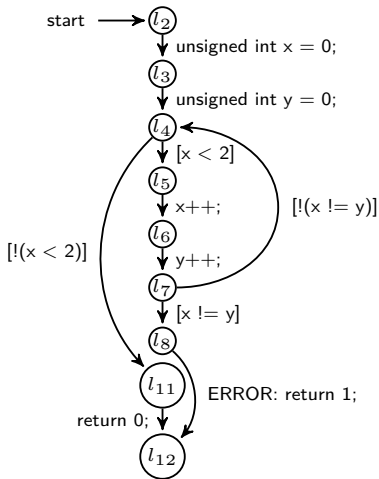
IMPACT: Example

with blk^l



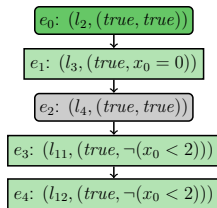
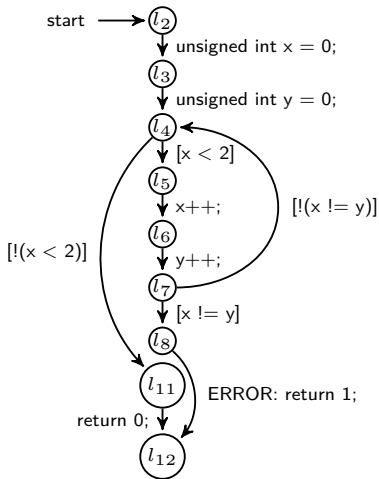
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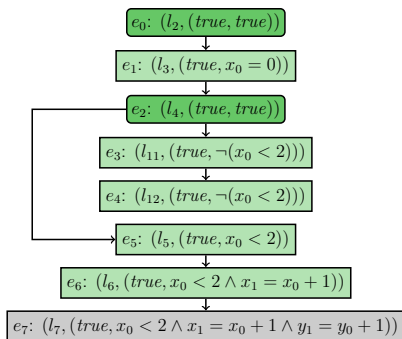
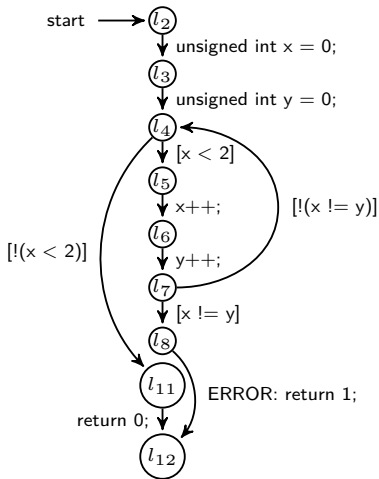
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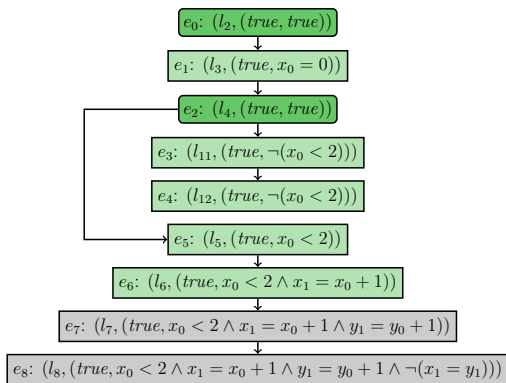
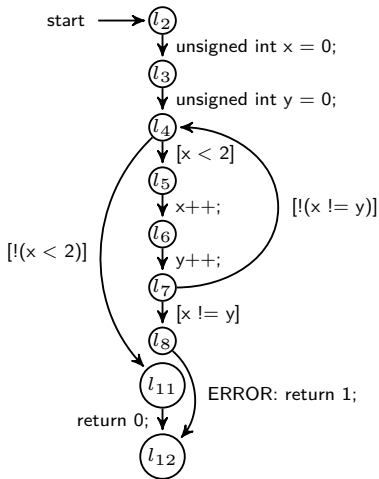
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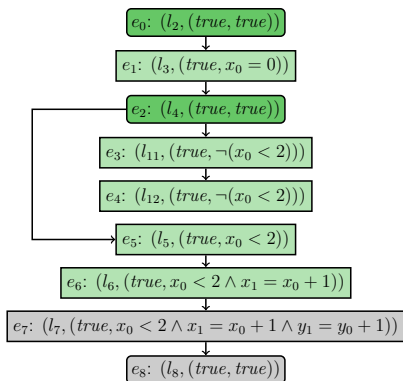
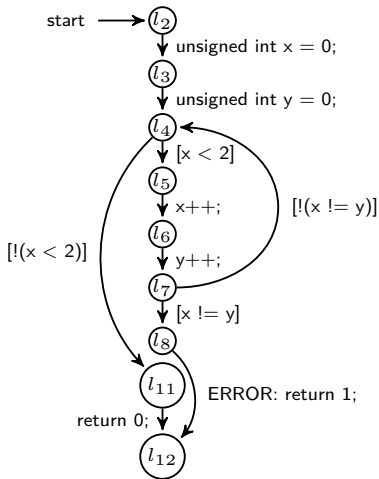
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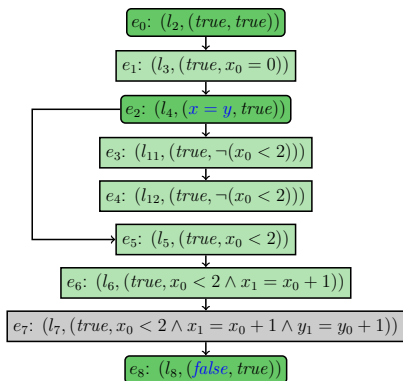
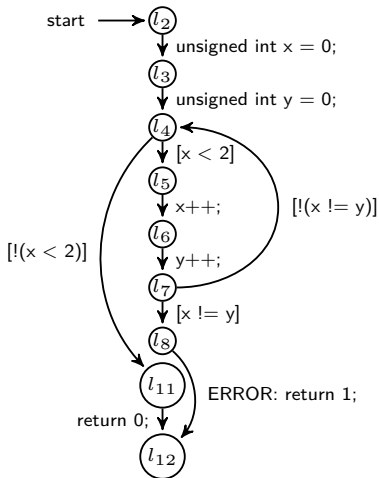
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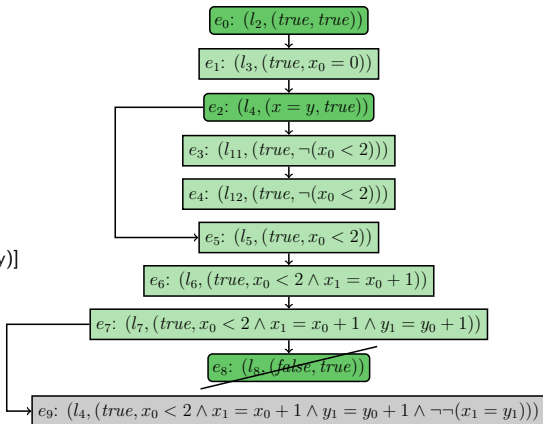
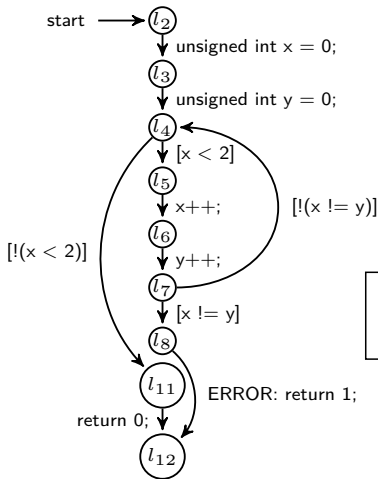
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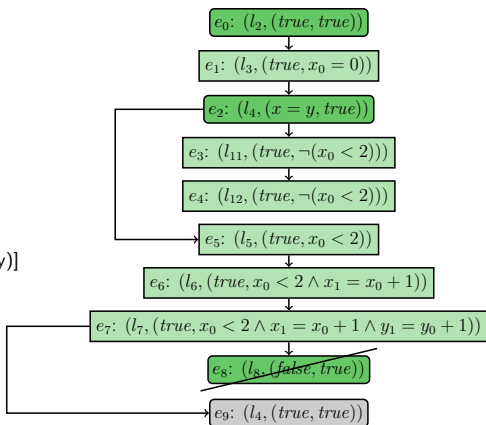
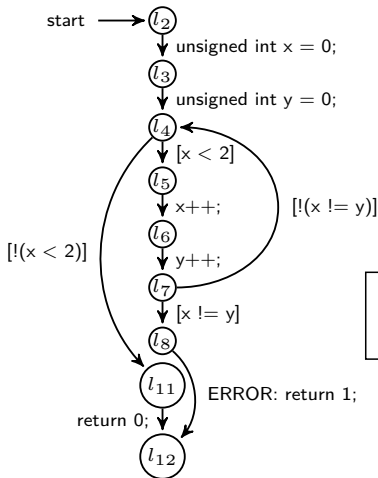
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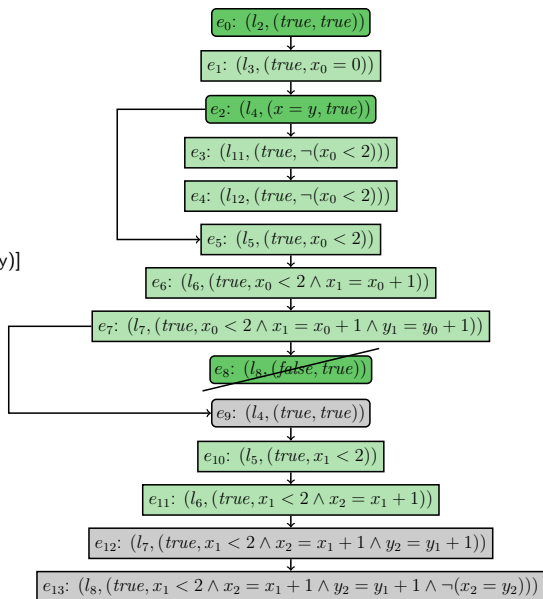
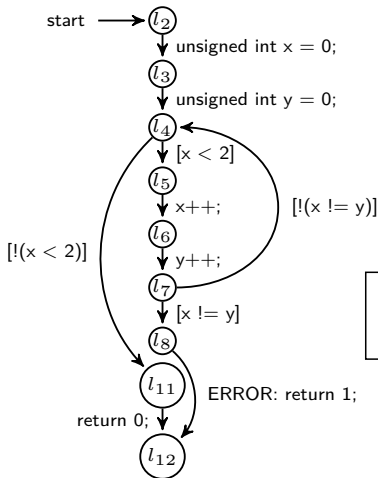
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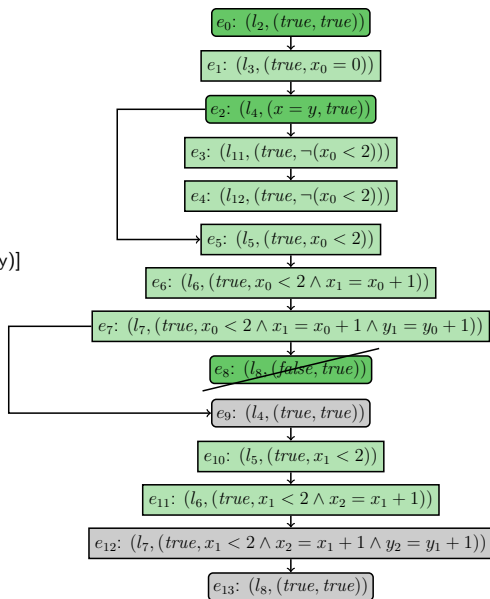
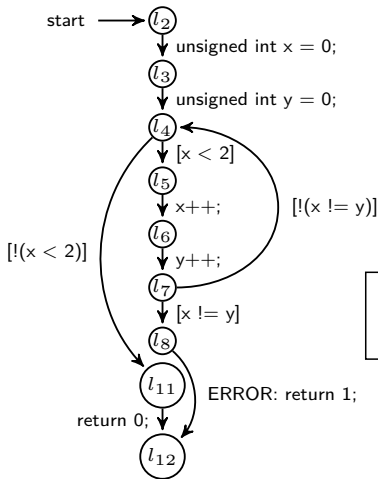
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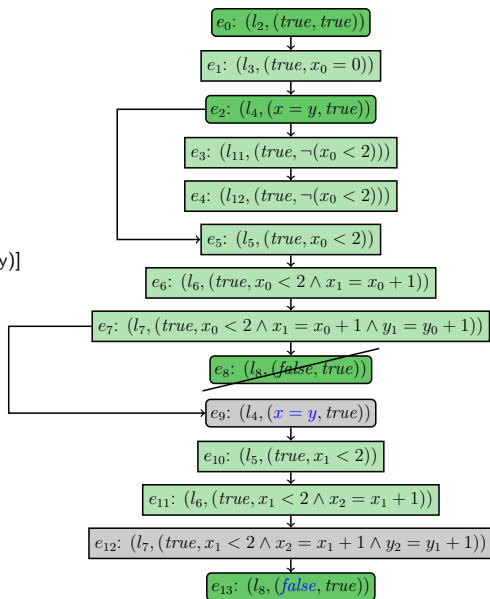
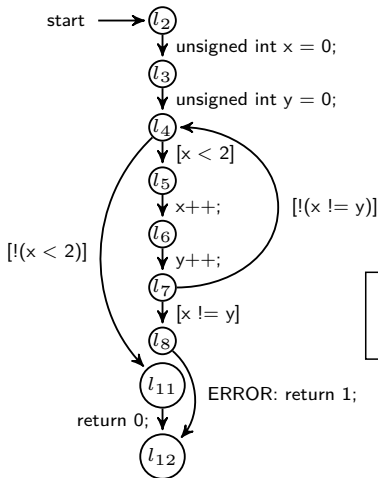
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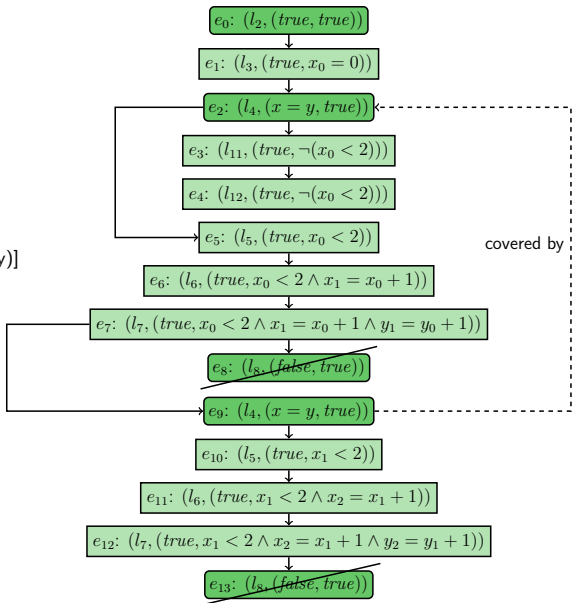
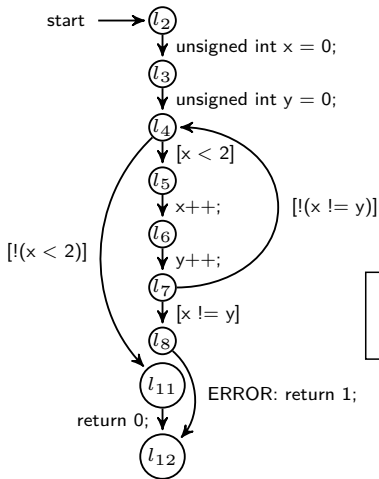
IMPACT: Example

with blk^l



IMPACT: Example

with blk^l



Bounded Model Checking

- ▶ Bounded Model Checking:
 - ▶ Biere, Cimatti, Clarke, Zhu: [TACAS'99]
 - ▶ No abstraction
 - ▶ Unroll loops up to a loop bound k
 - ▶ Check that P holds in the first k iterations:

$$\bigwedge_{i=1}^k P(i)$$

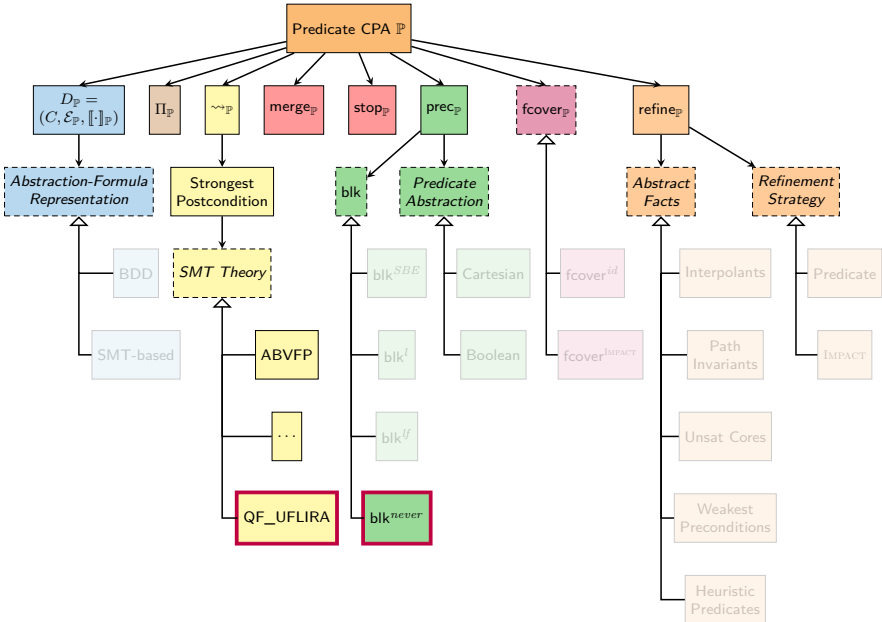
Expressing BMC

- ▶ Block Size (blk): blk^{never}

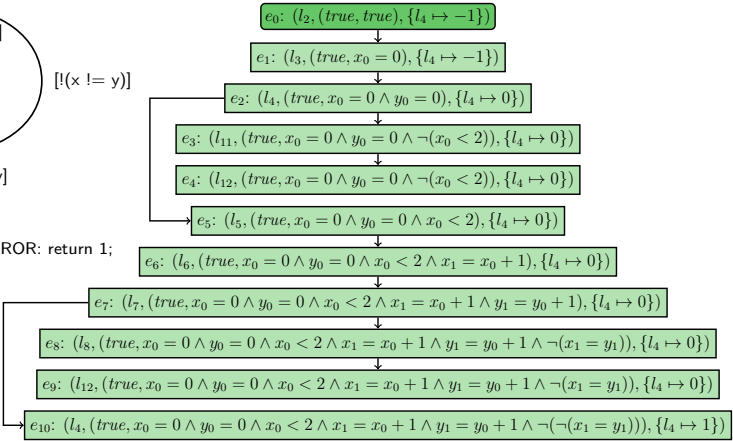
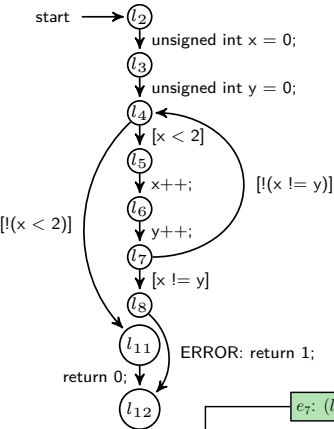
Furthermore:

- ▶ Add CPA for bounding state space (e.g., loop bounds)
- ▶ Choices for abstraction formulas and refinement irrelevant because block end never encountered
- ▶ Use Algorithm for iterative BMC:
 - 1: $k = 1$
 - 2: **while** !finished **do**
 - 3: run CPA Algorithm
 - 4: check feasibility of each abstract error state
 - 5: $k++$

Predicate CPA



Bounded Model Checking: Example with $k = 1$



1-Induction

- ▶ 1-Induction:

- ▶ Base case: Check that the safety property holds in the first loop iteration:

$$P(1)$$

→ Equivalent to BMC with loop bound 1

- ▶ Step case: Check that the safety property is 1-inductive:

$$\forall n : (P(n) \Rightarrow P(n + 1))$$

k -Induction

- ▶ k -Induction generalizes the induction principle:
 - ▶ No abstraction
 - ▶ Base case: Check that P holds in the first k iterations:
→ Equivalent to BMC with loop bound k
 - ▶ Step case: Check that the safety property is k -inductive:

$$\forall n : \left(\left(\bigwedge_{i=1}^k P(n+i-1) \right) \Rightarrow P(n+k) \right)$$

- ▶ Stronger hypothesis is more likely to succeed
- ▶ Add auxiliary invariants
- ▶ Kahsai, Tinelli: [\[PDMC'11\]](#)

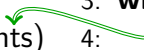
k -Induction with Auxiliary Invariants

Induction:

- 1: $k = 1$
- 2: **while** !finished **do**
- 3: BMC(k)
- 4: Induction(k , invariants)
- 5: $k++$

Invariant generation:

- 1: prec = <weak>
- 2: invariants = \emptyset
- 3: **while** !finished **do**
- 4: invariants = GenInv(prec)
- 5: prec = RefinePrec(prec)



k-Induction: Example

