

The next generation of formal verification tools

KeY Symposium 2026



Gidon Ernst

Interim Professor Software Engineering, University of Augsburg
Junior Professor Software Verification, LMU Munich

<https://www.sosy-lab.org/people/ernst/>



August 6, 2026

Foundations of the next generation of formal verification tools

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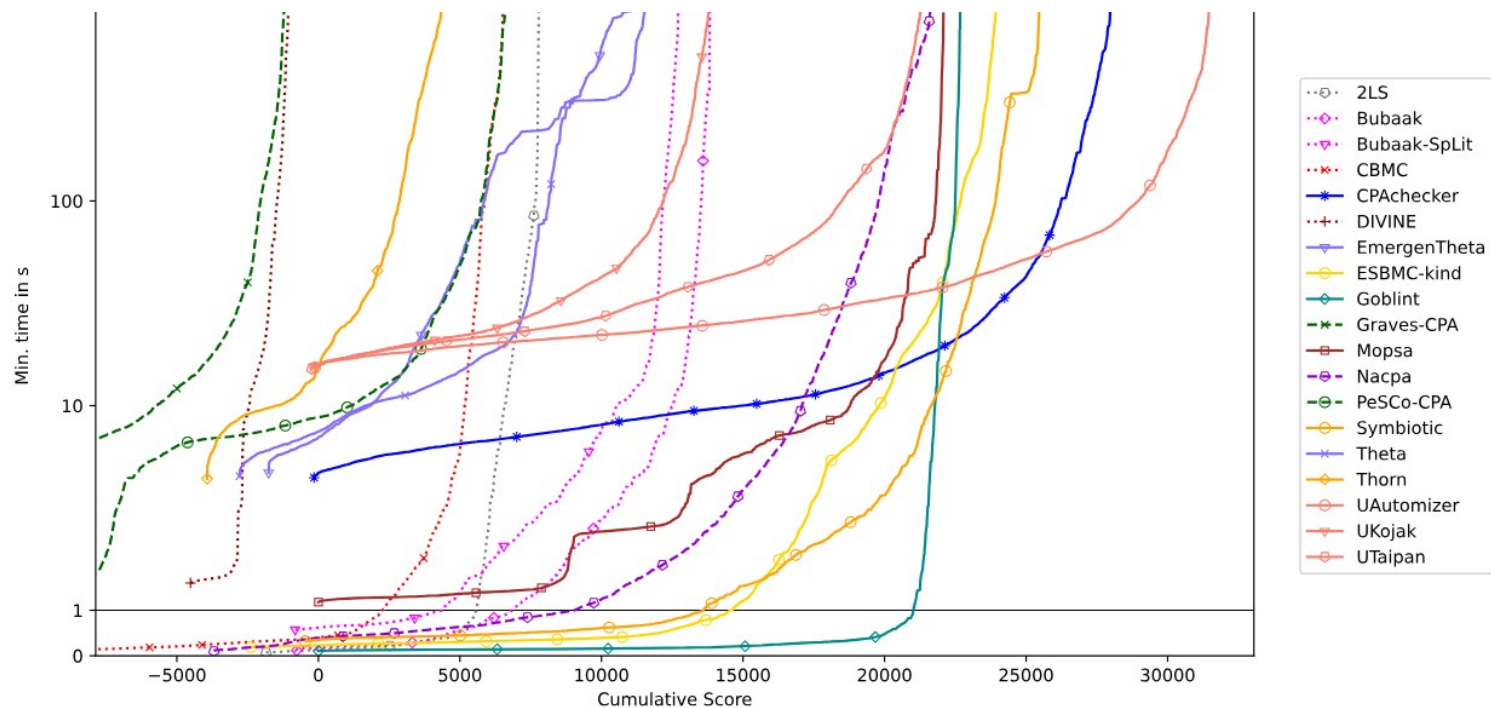
The current generation of tools

- they solve real and substantial problems

The current generation of tools

- they solve real and substantial problems





<https://sv-comp.sosy-lab.org/>



fully automatic
simpler properties



human-guided
expressive specs

A billion SMT queries a day

By [Neha Rungta](#)

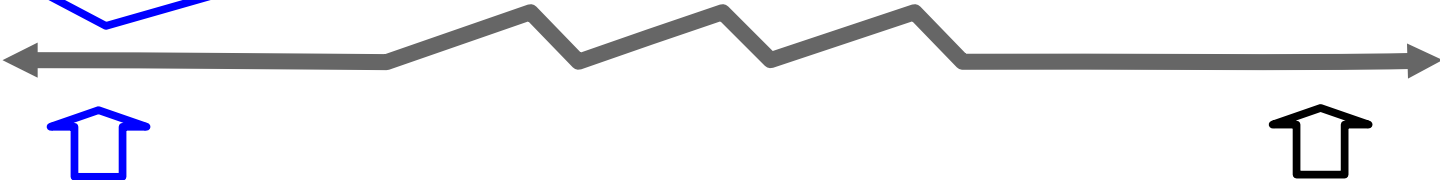
2022

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Amazon Web Services (AWS) is a cloud computing services provider that has made significant investments in applying formal methods to proving correctness of its internal systems and providing assurance of correctness to their end-users. In this paper, we focus on how we built abstractions and eliminated specifications to scale a verification engine for AWS access policies, Zelkova, to be usable by all AWS users. We present



fully automatic
simpler properties

human-guided
expressive specs

Fehler in Standardsortieralgorithmus mit formalen Methoden aufgedeckt

Android, Java und Groovy nutzen alle den TimSort-Algorithmus. Informatiker eines Verbundprojekts konnten mit Hilfe eines von ihnen entwickelten Tools nun einen Fehler in der Implementierung feststellen und beheben.

🔊 🖨️ 💬 115



<https://heise.de/-2570944>



fully automatic
simpler properties



human-guided
expressive specs

I AM401

Proving the correctness of AWS authorization

Lucas Wagner

(he/him)

Sr. Applied Science Manager
Amazon Web Services

Sean McLaughlin

(he/him)

Principal Applied Scientist
Amazon Web Services



fully automatic
simpler properties



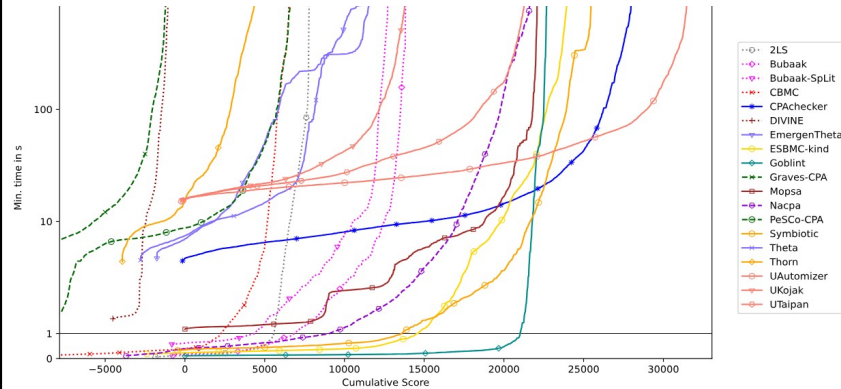
human-guided
expressive specs

The current generation of tools

- they solve real and substantial problems
- great! thanks for your attention. the end.

The current generation of tools

- they solve real and substantial problems
- great! we have come a long way but...
verification is still difficult



Fehler in Standardsortieralgorithmus mit formalen Methoden aufgedeckt

Android, Java und Groovy nutzen alle den TimSort-Algorithmus. Informatiker eines Verbundprojekts konnten mit Hilfe eines von ihnen entwickelten Tools nun einen Fehler in der Implementierung feststellen und beheben.

🔊 🖨️ 💬 115



fully automatic
simpler properties

open challenge

human-guided
expressive specs

Closing the verification loop: Observability-driven harnesses for building with agents

AI

HARNESS ENGINEERING

PUBLISHED

Mar 9, 2026

READ TIME

12m



Alp Keles



Sesh Nalla



Jai Menon



Vyom Shah

AI agents can now produce software faster than any team can verify it. The bottleneck has moved from writing code to trusting what was written.

Why bother at all?

“the bottleneck has moved from writing code to trusting what was written”

<https://www.datadoghq.com/blog/ai/harness-first-agents/>

TLA+ Specs (specs/tla/*.tla)

mirrors

Shared Invariants (src/invariants/)
SINGLE SOURCE

used by

Stateright
(all states)
30-60s

DST Tests
(~5s, 500
seeds)

THE WORKHORSE — 95%
of verification time

Kani
(bounded
~60s)

Staging Telemetry
(DDSQL: metrics,
logs, traces)

The current generation of tools

- they solve real and substantial problems
- great! we have come a long way but...
verification is still difficult but worthwhile
- what are we doing and are we doing it right?



Claims

- Invariants are a bad representation of correctness arguments
- Lemmas and auxiliary definitions are often a severe bottleneck
- Algorithmic inference is a bad method for routine tasks
- Incremental reasoning is essential for complex tasks

(much of this is widely accepted)

Claims

- Invariants are a bad representation of correctness arguments
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- Incremental reasoning is essential for complex tasks

Floyd/Hoare logic and invariants

```
while i < n  
  a[i] := z  
  i := i + 1
```

```
assert  
  i = n &&  
  a[k] = z
```

$$0 \leq i \leq n$$

$$\text{forall } j :: 0 \leq j < n \\ \implies a[j] = z$$

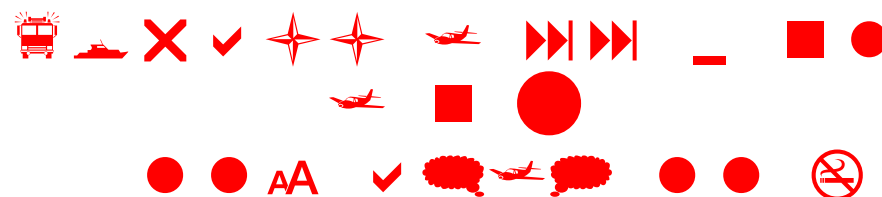
Lemma:

$$i \leq n \wedge \neg(i < n) \\ \implies i = n$$

Floyd/Hoare logic and invariants

```
while i < n
  a[i] := z
  i := i + 1
```

```
assert
  i == n &&
  a[k] == z
```



A much better explanation

```
while i < n  
  a[i] := z  
  i := i + 1
```

```
assert  
  i = n &&  
  a[k] = z
```

i counts from 0 to n

a is initialized to *z*
for all earlier *i*

Lemma:
when *i* counts from 0 to n
the final value is n

Trace Equation Systems (TEQs)

```
while i < n  
  i := i + 1  
  a[i] := z
```

```
assert  
  i = n &&  
  a[k] = z
```

$\hat{a}i = \text{counter}(\emptyset, n)$

$\hat{a}a = \text{stores}(a^0, \hat{a}i, \text{const}(z))$

$\text{current}(\text{counter}(\emptyset, n)) = n$

Trace Equation Systems (TEQs)

```
while i < n  
  i := i + 1  
  a[i] := z
```

```
assert  
  i = n &&  
  a[k] = z
```

$\textcolor{teal}{@i} = \textcolor{blue}{\text{counter}(0, n)}$

$\textcolor{teal}{@a} = \textcolor{blue}{\text{stores}(a^0, \textcolor{teal}{@i}, \textcolor{blue}{\text{const}(z)})}$

$\textcolor{violet}{\text{current}(\textcolor{blue}{\text{stores}(a^0, \textcolor{teal}{@k}, \textcolor{teal}{@v})})[k]}$
 $\textcolor{blue}{=}$ if $k \in \textcolor{teal}{@k}$
then $\textcolor{black}{\text{get}(\textcolor{black}{\text{pos}(k, \textcolor{teal}{@k})}, \textcolor{teal}{@v})}$
else $a^0[k]$

Claims

- Invariants are a bad representation of correctness arguments
- Lemmas and auxiliary definitions are often a severe bottleneck
[Baumann & Beckert 12]
- Algorithmic inference is a bad method for routine tasks
- Incremental reasoning is essential for complex tasks

“Annotation inference is the problem”

$$\frac{\exists I. \quad P \Rightarrow I \quad \{I \wedge \phi\} c \{I\} \quad I \wedge \neg \phi \Rightarrow Q}{\{P\} \text{ while } \phi \text{ do } c \{Q\}}$$

“Annotation inference is the problem”

has trivial solution:

(assume ϕ ; c)*

(think: ACL2, rippling)

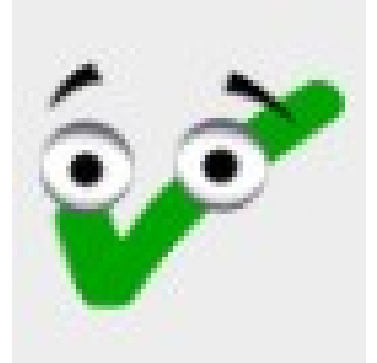
$$\frac{\exists I. \quad P \Rightarrow I \quad \{I \wedge \phi\} c \{I\} \quad I \wedge \neg \phi \Rightarrow Q}{\{P\} \text{ while } \phi \text{ do } c \{Q\}}$$

Current boundary of automation

```
for i = 0..n  
  s += a[i]
```

```
for i = 0..n  
  s -= a[i]
```

```
assert  
  s == 0
```



Current deductive approach

program

```
for i = 0 .. n
  s += a[i]

for i = 0 .. n
  s -= a[i]

assert
  s == 0
```

logic

```
fun sum(i,n,a) {
  if 0 ≤ i < n
  then a[i]+sum(i+1,n,a)
  else 0
}
```



```
for i = 0..n  
  s += a[i]
```

```
sum(i,n,a) =  
  if  $0 \leq i < n$   
  then  
    a[i] + sum(i+1,n,a)  
  else  
    0
```

**Corporate needs you to find the differences
between this picture and this picture.**



They're the same picture.

Use of lemmas for code with auxiliary functions

lemma:
empty sum
is zero

lemma:
sum unfolds well
(depends on def.)

lemma:
sum is linear,
...

$$\frac{\exists I. \quad P \Rightarrow I \quad \{I \wedge \phi\} c \{I\} \quad I \wedge \neg \phi \Rightarrow Q}{\{P\} \text{ while } \phi \text{ do } c \{Q\}}$$

Claims

- Invariants are a bad representation of correctness arguments
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- Incremental reasoning is essential for complex tasks

“Model checking is dead”

(famous person at CAV, reportedly)

Algorithmic invariant inference

```
i = 0
```

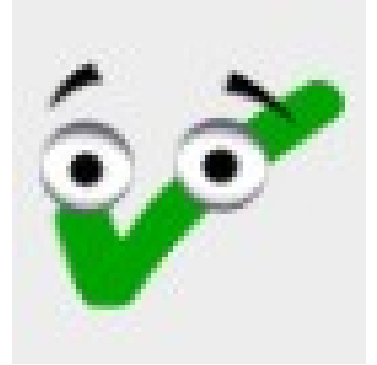
```
while i < n
```

```
    i += 1
```

```
    ...
```

```
assert
```

```
    i == n
```



Algorithmic invariant inference

```
i = 0
```

```
while i < n
```

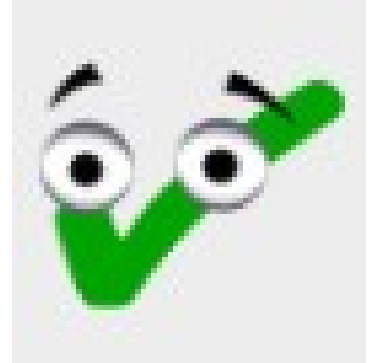
```
    i += 1
```

```
    ...
```

```
assert
```

```
    i = n
```

$\text{true} \wedge \neg(i < n)$
 $\Rightarrow i = n ?$



Algorithmic invariant inference

```
i = 0
```

```
while i < n
```

```
  i += 1
```

```
  ...
```

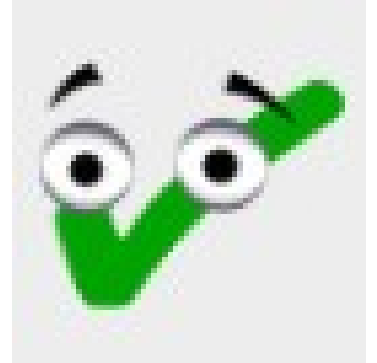
```
assert
```

```
  i = n
```

$\text{true} \wedge \neg(i < n)$

$\Rightarrow i = n ?$

no. let me see if
the CEX is
reachable ...



Algorithmic invariant inference

```
i = 0
```

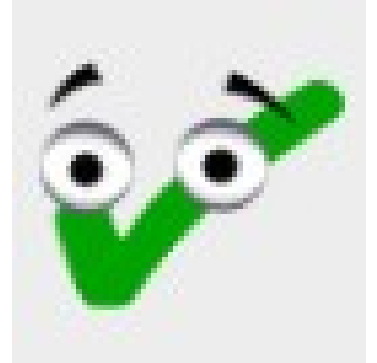
```
while i < n  
  i += 1
```

```
...
```

```
assert  
  i = n
```

$\text{true} \wedge \neg(i < n)$
 $\Rightarrow i = n ?$

no.
CEX not real.



Algorithmic invariant inference

```
i = 0
```

```
while i < n
```

```
  i += 1
```

```
  ...
```

```
assert
```

```
  i = n
```

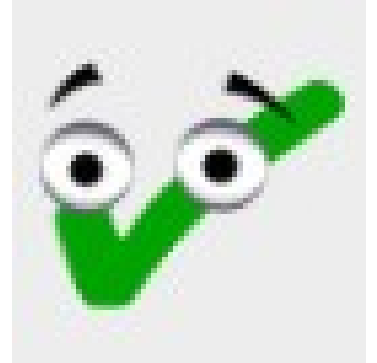
$\text{true} \wedge \neg(i < n)$

$\Rightarrow i = n ?$

no.

CEX not real.

let me
interpolate that
for you!



Algorithmic invariant inference

```
i = 0
```

```
while i < n
```

```
    i += 1
```

```
    ...
```

```
assert
```

```
    i = n
```

```
true  $\wedge$   $!(i < n)$ 
```

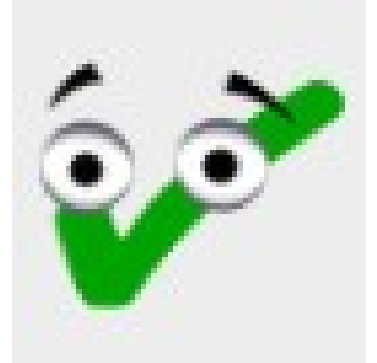
```
 $\Rightarrow i = n$  ?
```

```
no.
```

```
CEX not real.
```

```
interpolant:
```

```
 $i \leq n$ 
```



Algorithmic invariant inference

```
i = 0
```

```
while i < n
```

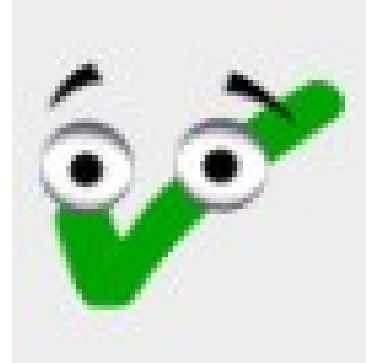
```
  i += 1
```

```
  ...
```

```
assert
```

```
  i = n
```

```
i ≤ n ∧  
  !(i < n)  
⇒ i = n ?
```



Algorithmic invariant inference

```
i = 0
```

```
while i < n
```

```
    i += 1
```

```
    ...
```

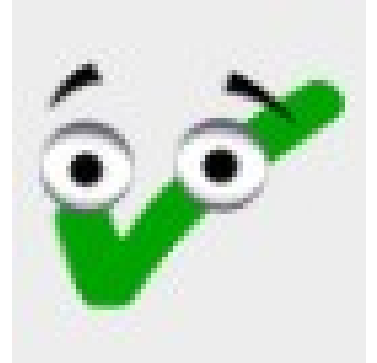
```
assert
```

```
    i == n
```

```
i ≤ n ∧  
    !(i < n)  
⇒ i = n ?
```

yes.

you are right!
it's a counter



Invariants from known principles

```
i = 0
```

```
while i < n
```

```
    i += 1
```

```
    ...
```

```
assert
```

```
    i = n
```

loop acceleration:
i counts from 0 to n



Claims

- Invariants are a bad representation of correctness arguments
- Lemmas and auxiliary definitions are often a severe bottleneck
- Algorithmic inference is a bad method for routine tasks
- Incremental reasoning is essential for complex tasks

“Interaction of is coming back”

(Bernhard Steffen, yesterday)

Access to (useful) intermediate results?

```
for i = 0..n  
  s += a[i]
```

```
for i = 0..n  
  s -= a[i]
```

```
assert  
  s == 0
```

```
first loop:  
0 ≤ i ≤ n
```

```
second loop:  
0 ≤ i ≤ n
```

```
let me unroll that
```

```
...
```

```
a[0] - a[0] = 0
```

```
a[0] + a[1]
```

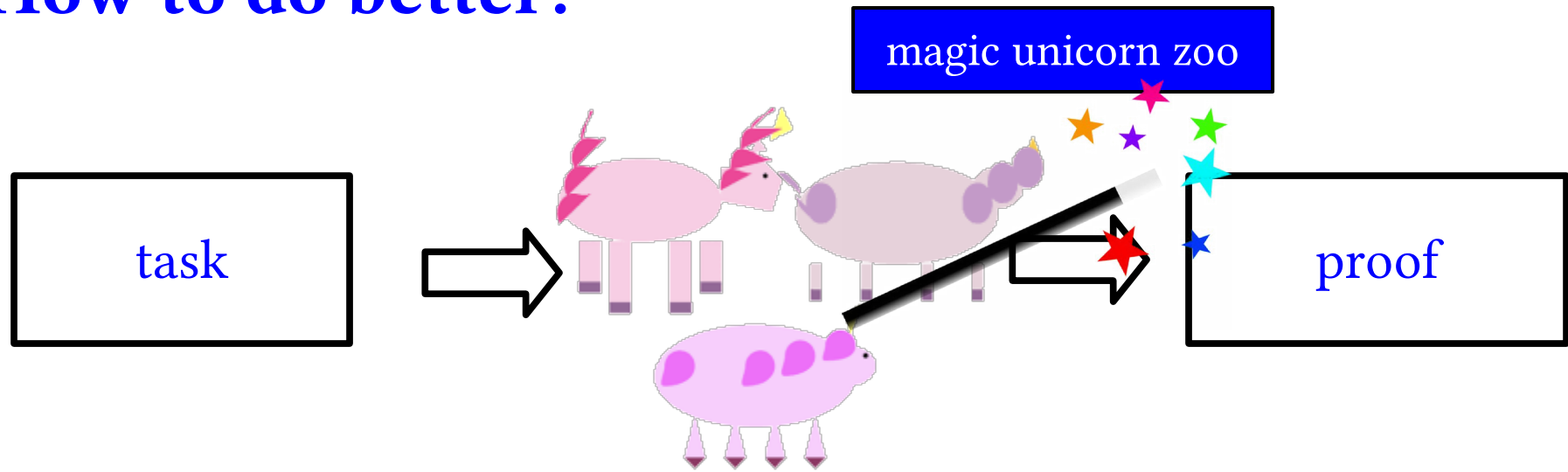
```
  - a[0] - a[1] = 0
```

```
...
```

```
(timeout)
```



How to do better?



How to do better?

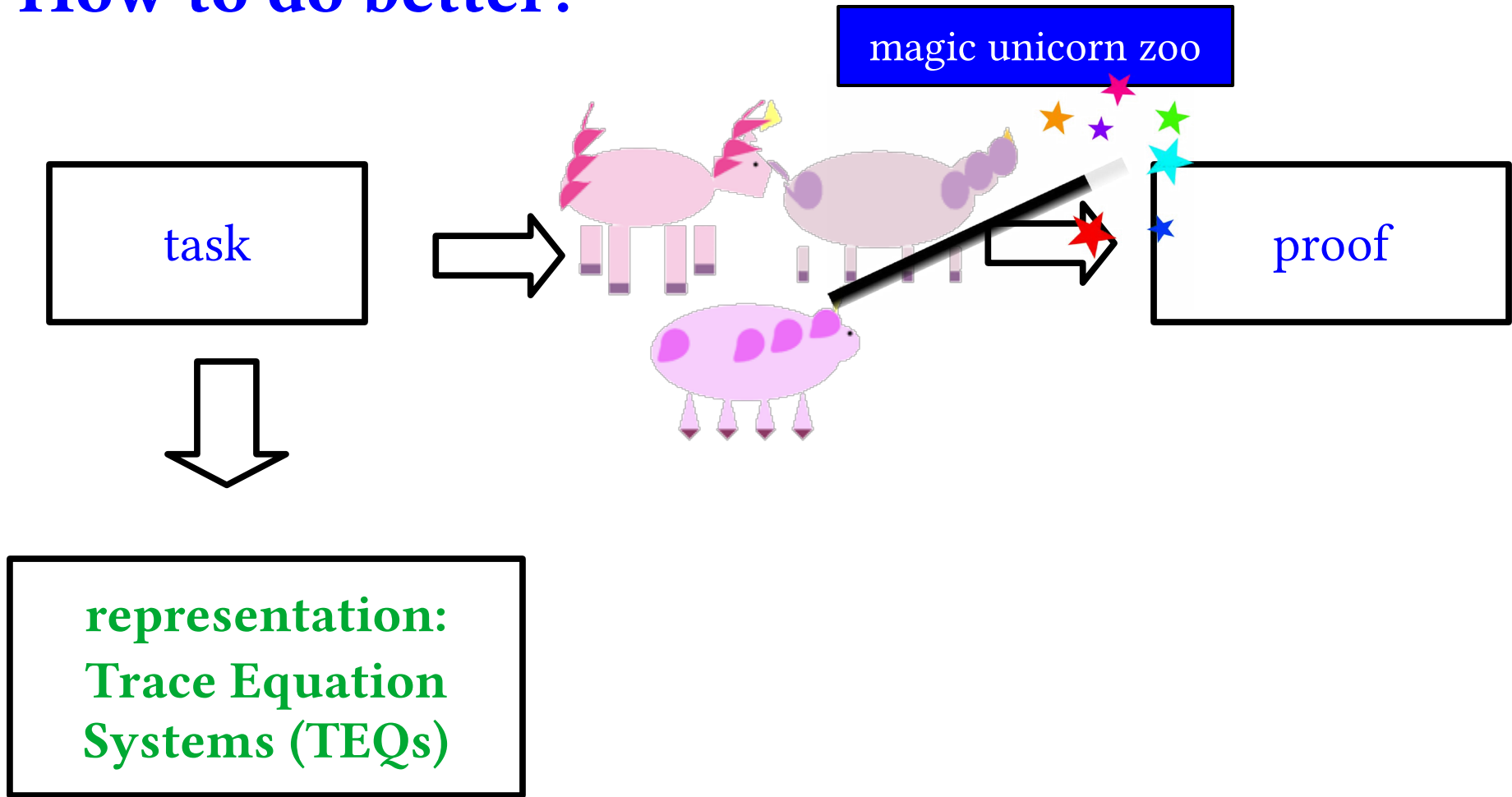
Why are LLMs good?

How to do better?

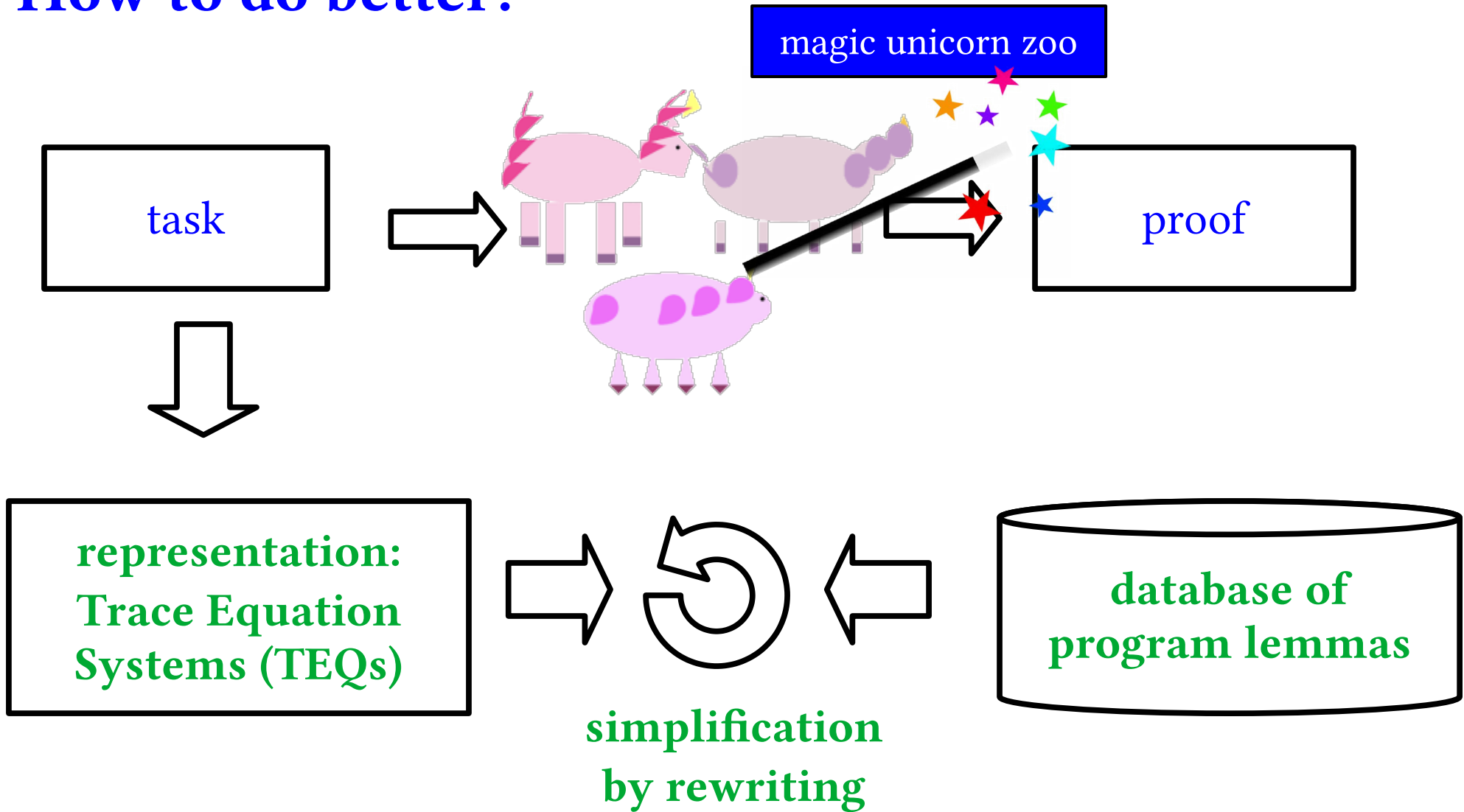
Why are LLMs good?

1. have effective problem representation
2. know the solution

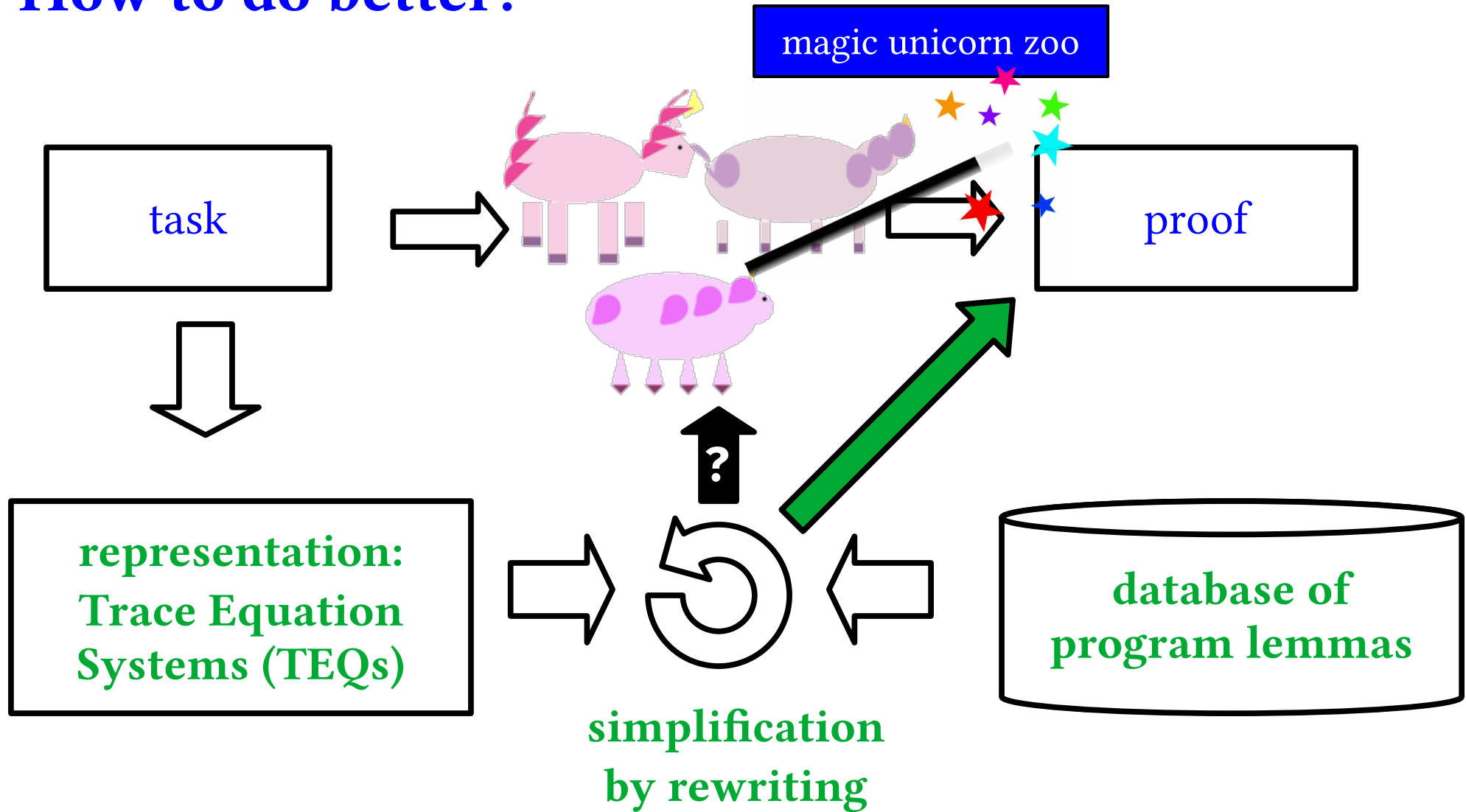
How to do better?



How to do better?



How to do better?



TEQs are a “variable-modular” representation

$\text{@xs} = \text{trace}(\text{init}, \text{for } \underbrace{y \leftarrow \text{ys}}_{\text{dependencies}} \text{ do } \underbrace{x := u(x, y)}_{\text{update rule}})$

$\underbrace{x}_{\text{program variable}} = \text{current}(\text{@xs})$

$\text{current}(\text{trace}(\text{init}, \text{ys}, \text{upd}))$
 $= \text{foldl}(\text{init}, \text{ys}, \text{upd})$

TEQs enable algebraic reasoning

@is = trace(init, for k ← ks do i := i + 1)
 $\rightsquigarrow$ range(0, 1, |ks|)

i = current(@is)
 $\rightsquigarrow$ |ks|

current(range(a, c, n))
 $\underline{\underline{\text{lemma}}}$ a + c*n

DEMO

array init, summation

Trace Equation Systems: Evaluation

Benchmark	# Tasks	TEQ		TEQ+Z3		Reference	
		✓	err	✓	err		
MaxPranq	17	16	0	16	0	MaxPranq †	17
Rapid	33	14	0	15	0	Rapid	30
Σ MonoCera	150	52	10	62	23	MonoCera	63
min	17	7	0	10	0	9	
max	12	5	3	5	3	8	
sum	26	5	3	6	7	16	
forall	96	35	7	41	13	30	
Arrays (safe)	320	68	32	86	‡ 87	Symbiotic *	68
Loops (safe)	551	44	146	71	158	aise *	405

Trace Equation Systems for Program Verification

[Coenen, Ernst, submitted 2026]

Contribution: New foundations

Trace Equation Systems for Program Verification

[Coenen, Ernst, submitted 2026]

Contribution: New foundations

TEQs represent constraints from loops

- view a the loop as its own specification – but enable tractable automation
- syntactic, sound, complete → retain expressiveness
- isolate program fragments → compositional reasoning

Trace Equation Systems for Program Verification

[Coenen, Ernst, submitted 2026]

Contribution: New foundations

TEQs represent constraints from loops

- view a the loop as its own specification – but enable tractable automation
- syntactic, sound, complete → retain expressiveness
- isolate program fragments → compositional reasoning

TEQs support incremental verification

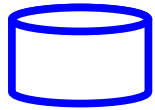
- reason by program transformation – with an algebraic rewrite theory
- lemmas to give names to program fragments (counter, array copy, ...)
- lemmas to explain program fragments some contexts (comparison, lookup, ...)

Trace Equation Systems: Current Status

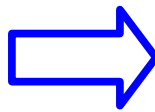
- Theory (including Isabelle/HOL formalization)
- Tool (most capabilities, still prototype)

Trace Equation Systems: Current Status

- Theory (including Isabelle/HOL formalization)
- Tool (most capabilities, still prototype)
- Lemma database and reasoning principles



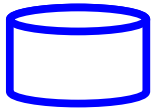
counters, array lookup + update, summations



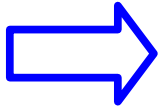
next steps: learn how to deal with more complex code

Trace Equation Systems: Current Status

- Theory (including Isabelle/HOL formalization)
- Tool (most capabilities, still prototype)
- Lemma database and reasoning principles

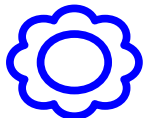


counters, array lookup + update, summations

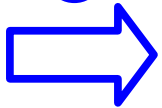


next steps: learn how to deal with more complex code

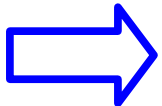
- Evaluation



so far: promising results without overly specific lemmas



next steps: cover entire benchmark set, extract principles



later steps: real-world code

Some related work (in parts motivating/subsumed)

- CHCs: canonical “state-modular” representation
- TEQs: canonical “variable-modular” representation
- Bundy+ [93], Unno [17] goal-directed induction
- Dacca+ [CAV 16] Array Folds Logic
- Frohn [TACAS 20] modular acceleration calculus
- Georgiou+ [FMCAD 20] Trace Logic
- Chakraborty+ [TACAS 20, CAV 21] transformations
- Amilon+ [CAV 23] instrumentation + CHCs
- Frohn [CAV 26] acceleration of array lookups

Outlook and Discussion

- What's the scope & limitations of TEQs?
Notably: how to treat recursive procedures?
- How to combine with traditional methods?
- How to build interaction around TEQs?
- How to infer lemmas automatically?
LemmaCalc [Ernst, Fedyukovich iFM 2025]

On the abstraction level of interactive proofs

But AI...

RESEARCH

Leanstral: Open-Source foundation for trustworthy vibe-coding

March 16, 2026 By Mistral AI

<https://mistral.ai/news/leanstral/>

```
42  /-- Left rotation, applied at a node whose right child is itself a node.
43      If the right child is a leaf there is nothing to rotate, and we
44      return the tree unchanged (the standard convention). -/
45  def rotateLeft : Tree  $\alpha$   $\rightarrow$  Tree  $\alpha$ 
46      | node l x (node r1 y rr) => node (node l x r1) y rr
47      | t => t
48
49  /-! ### 1. Rotation preserves the multiset (here: the exact sequence) of elements -/
50
51  theorem rotateLeft_toList (l : Tree  $\alpha$ ) (x :  $\alpha$ ) (r1 : Tree  $\alpha$ ) (y :  $\alpha$ ) (rr : Tree  $\alpha$ ) :
52      toList (rotateLeft (node l x (node r1 y rr)))
53      = toList (node l x (node r1 y rr)) := by
54  (+) simp only [rotateLeft, toList, List.append_assoc]
```

```
42  /-- Left rotation, applied at a node whose right child is itself a node.
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53      = toList (node l x (node r1 y rr)) := by
54      simp only [rotateLeft, toList, List.append_assoc]
```

**not principled
approach**

```

56 /-! ### 2. Rotation preserves the BST invariant -/
57
58 theorem rotateLeft_BST [LT  $\alpha$ ] (lt_trans :  $\forall \{a \ b \ c : \alpha\}, a < b \rightarrow b < c \rightarrow a < c$ )
59   (l : Tree  $\alpha$ ) (x :  $\alpha$ ) (r1 : Tree  $\alpha$ ) (y :  $\alpha$ ) (rr : Tree  $\alpha$ )
60   (h : BST ( $\alpha := \alpha$ ) (node l x (node r1 y rr))) :
61   BST ( $\alpha := \alpha$ ) (rotateLeft (node l x (node r1 y rr))) := by
62   obtain ⟨hlx, hxRight, hBSTl, hBSTright⟩ := h
63   obtain ⟨hrly, hyrr, hBSTrl, hBSTrr⟩ := hBSTright
64   have hxy :  $x < y$  := hxRight y (by simp [toList])
65   have hxrl :  $\forall z \in \text{toList } r1, x < z$  := by
66     intro z hz
67     exact hxRight z (by simp [toList]; exact Or.inl hz)
68   have hBSTlxl : BST ( $\alpha := \alpha$ ) (node l x r1) := ⟨hlx, hxrl, hBSTl, hBSTrl⟩
69   have hleftY :  $\forall z \in \text{toList } (\text{node l x r1}), z < y$  := by
70     intro z hz
71     simp only [toList, List.mem_append, List.mem_singleton] at hz
72     rcases hz with (hzl | hzeq) | hzrl
73     · exact lt_trans (hlx z hzl) hxy
74     · exact hzeq ▸ hxy
75     · exact hrly z hzrl
76 (+) exact ⟨hleftY, hyrr, hBSTlxl, hBSTrr⟩

```

```

56 /-! ### 2. Rotation preserves the BST invariant -/
57
58 theorem rotateLeft_BST [LT  $\alpha$ ] (lt_trans :  $\forall \{a\ b\ c : \alpha\}, a < b \rightarrow b < c \rightarrow a < c$ )
59   (l : Tree  $\alpha$ ) (x :  $\alpha$ ) (r1 : Tree  $\alpha$ ) (y :  $\alpha$ ) (rr : Tree  $\alpha$ )
60   (h : BST ( $\alpha := \alpha$ ) (node l x (node r1 y rr))) :
61   BST ( $\alpha := \alpha$ ) (rotateLeft (node l x (node r1 y rr))) := by
62   obtain ⟨hlx, hxRight, hBSTl, hBSTright⟩ := h
63   obtain ⟨hrly, hyrr, hBSTrl, hBSTrr⟩ := hBSTright
64   have hxy :  $x < y := hxRight\ y$  (by simp [toList])
65   have hxrl :  $\forall z \in \text{toList } r1, x < z := by$ 
66     intro z hz
67     exact hxRight z (by simp [toList]; exact Or.inl hz)
68   have hBSTlxl : BST ( $\alpha := \alpha$ ) (node l x r1) := ⟨hlx, hxrl, hBSTl, hBSTrl⟩
69   have hleftY :  $\forall z \in \text{toList } (\text{node l x r1}), z < y := by$ 
70     intro z hz
71     simp only [toList, List.mem_append, List.mem_singleton] at hz
72     rcases hz with (hzl | hzeq) | hzrl
73     · exact lt_trans (hlx z hzl) hxy
74     · exact hzeq ▸ hxy
75     · exact hrly z hzrl
76 (+) exact ⟨hleftY, hyrr, hBSTlxl, hBSTrr⟩

```

$\approx$ assembler

```

fun content where
  "content Leaf = []" |
  "content (Node l x r) = content l @ [x] @ content r"

```

```

fun BST where
  "BST Leaf = True" |
  "BST (Node l x r) = (( $\forall y \in \text{set } (\text{content } l). y < x$ )"

```

```

fun rotate_left where
  "rotate_left (Node l x (Node rl y rr)) = Node (Node
  "rotate_left t = t"

```

```

lemma content_rotate_left:
  "content (rotate_left t) = content t"
  sledgehammer
  by (smt (verit) append_assoc content.simps(2) rotate_left.elims)

```

```

lemma BST_rotate_left:
  fixes t :: "int tree"
  assumes "BST t"
  shows "BST (rotate_left t)"
  using assms
  by (cases t rule: rotate_left.cases) auto

```

good abstraction level:
hammer + lemmas
(here found automatically)

even better:
both lemmas have an
obvious, “canonical” proof

Further features of next generation of tools

- AI enabled
- high-level & explainable reasoning at the level of the problem domain and input language (e.g., boilerplate and internal representation is suppressed)
- actually support full programming languages & libraries
- interoperable: types of tools, shared frontends, testing
- flexible correctness concerns (e.g. security, underapproximation, trace- and hyperproperties)
- integrate better with SE (people, processes, toolchains, documentation)

Verification with Trace Equation Systems

